

Today's lecture PDF is online if you want to download and follow.

# PHY 117 HS2023

Week 2, Lecture 1

Sept. 26, 2023

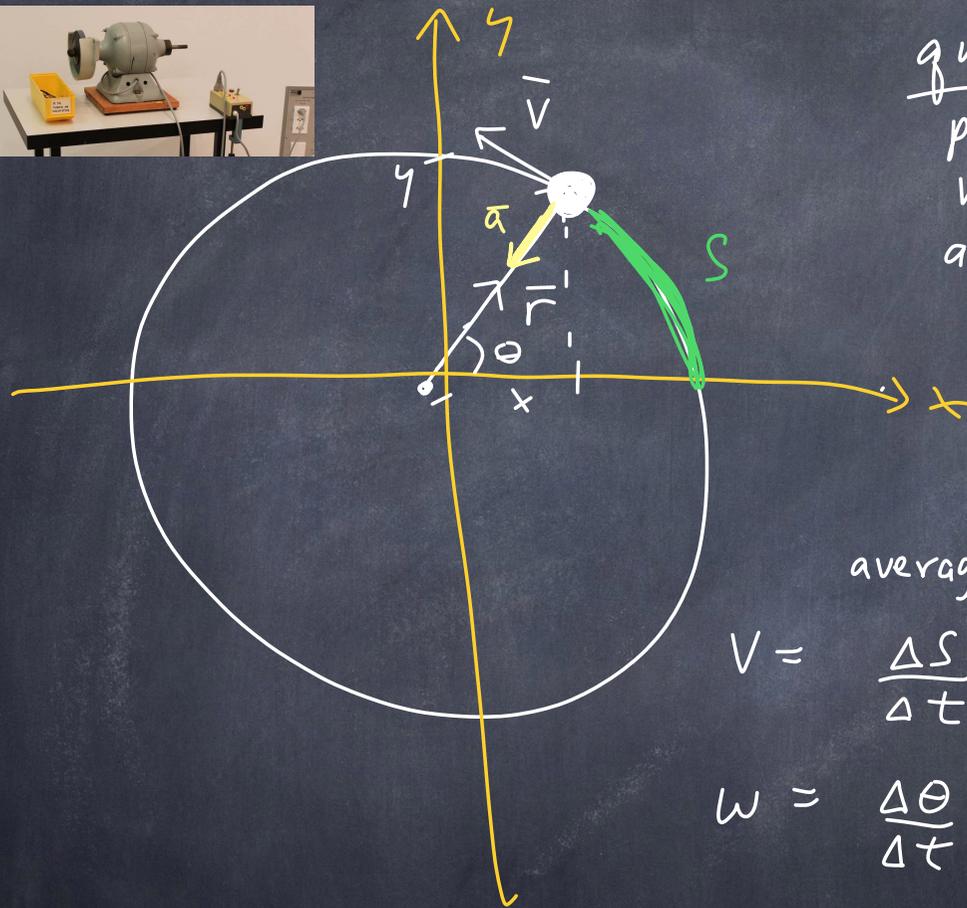
Prof. Ben Kilminster

Quiz:

The acceleration vector for an object moving in a circle is toward the center of the circle.

(Incorrect online)

# Circular motion (in 2D) at constant speed.



quantity	in terms of distance	in terms of angles	relation
position	$s$	$\theta$	$s = r\theta$
velocity	$v$	$\omega$	$v = r\omega$
acceleration	$a$	$\alpha$	$a = r\alpha$

$$a = \frac{v^2}{r} = \frac{(r\omega)^2}{r} = \omega^2 r$$

$$\alpha = \frac{a}{r} = \omega^2$$

average  $\rightarrow$  instantaneous

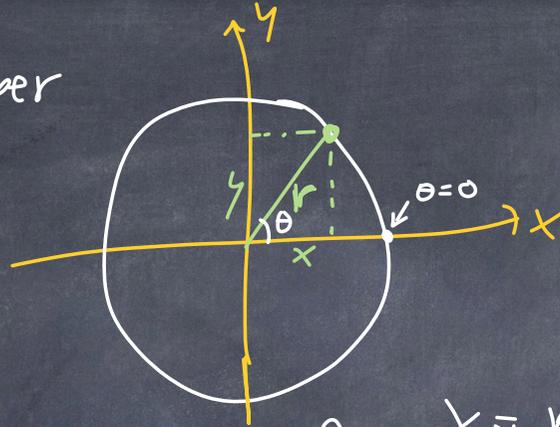
$$v = \frac{\Delta s}{\Delta t} \rightarrow \frac{ds}{dt}$$

$$\omega = \frac{\Delta \theta}{\Delta t} \rightarrow \frac{d\theta}{dt}$$

$$\alpha = \frac{\Delta \omega}{\Delta t} \rightarrow \frac{d\omega}{dt}$$

Equation of motion for constant speed:  $\theta = \omega t + \theta_0$   
 $\uparrow$   
initial angle

Remember



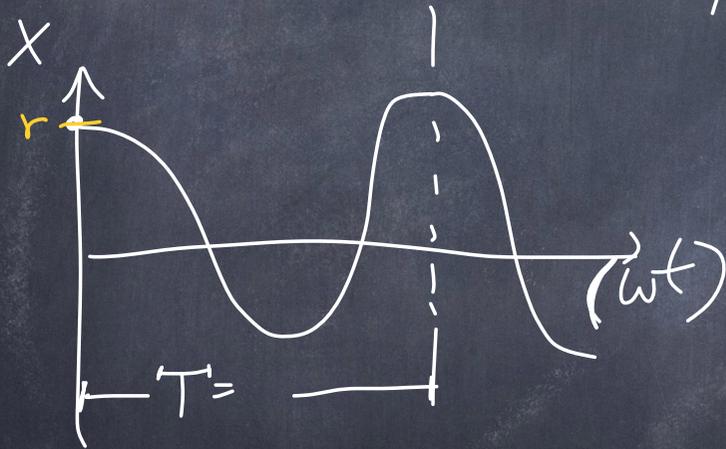
$$x = r \cos \theta$$

$$y = r \sin \theta$$

If speed is constant,  
then  $\theta = \omega t$

$$\text{so } x = r \cos(\omega t)$$

$$y = r \sin(\omega t)$$

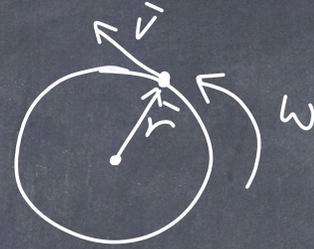
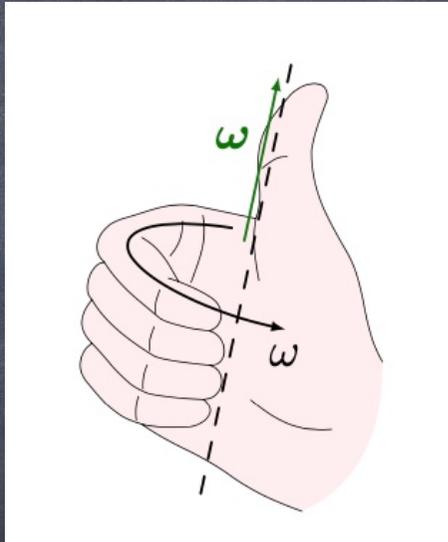


$$T = \frac{2\pi}{\omega} = \frac{2\pi r}{v}$$



Notice: circular motion  
means  $x$  &  $y$   
components  
are simple harmonic  
oscillators.

# Direction of $\vec{\omega}$ vector



picture:  $\vec{\omega}$  is out of the page

⊙ arrow coming towards you

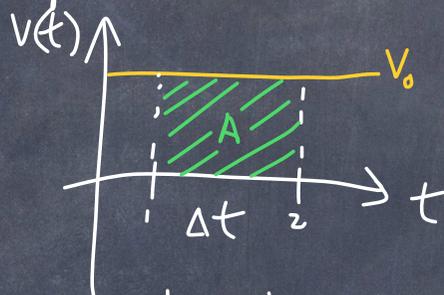
If  $\vec{\omega}$  is into the page, we use ⊗ (arrow moving away)

we have seen that  $\frac{dv}{dt} = a$  : the slope of  $v$  vs.  $t$  is the acceleration

$\frac{dx}{dt} = v$  : the slope of  $x$  vs.  $t$  is the velocity

Consider a particle moving at constant velocity:

$$v(t) = v_0 = \text{constant}$$

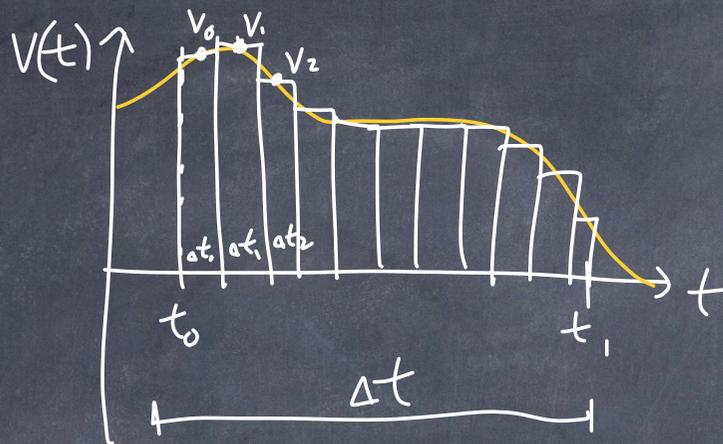


we know that  $v_0 = \frac{\Delta x}{\Delta t} \Rightarrow \Delta x = v_0 \Delta t$

from the figure we see that  $v_0 \Delta t$  is the area of the rectangle  $A = v_0 \Delta t$

So the change in position  $\Delta x$  is the area under the  $v$  vs.  $t$  curve.

For a more complicated  $V$  vs.  $t$  curve:



We can approximate  $\Delta X$  by summing up many small rectangles

$$x_1 - x_0 = \Delta X = \sum_i V_i \Delta t_i$$

As  $\Delta t_i$  gets smaller, we get more precise

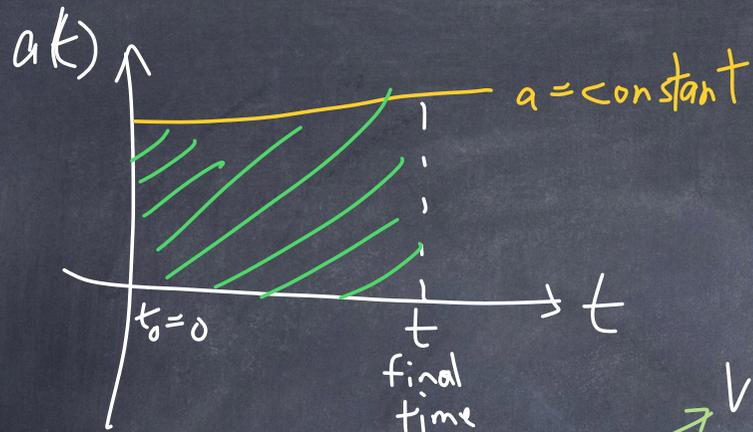
$$\Delta X = \lim_{\Delta t_i \rightarrow 0} \sum_i V_i \Delta t_i = \int_{t_0}^{t_1} V dt$$

So  $\Delta X$  = the integral of the  $V$  vs.  $t$  curve from  $t_0$  to  $t_1$

Likewise,  $\Delta V = \lim_{\Delta t_i \rightarrow 0} \sum_i a_i \Delta t_i = \int_{t_0}^{t_1} a dt$



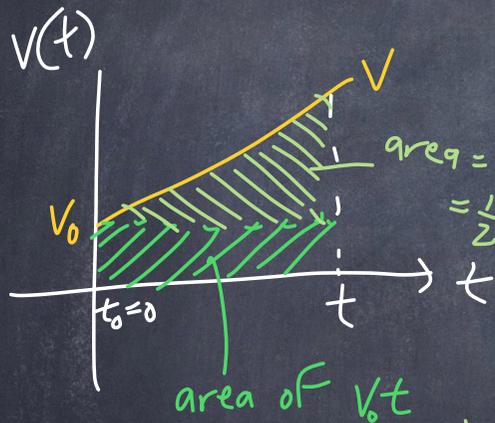
$\Delta V$  = area of curve under  $a$  vs.  $t$



$$\Delta V = V - V_0 = \int_{t_0=0}^t a \, dt = \left[ at \right]_0^t = at - 0 = at$$

$$V - V_0 = at \rightarrow \boxed{V = V_0 + at}$$

formula from last week



$$\Delta x = x - x_0 = \int_{t_0=0}^t V \, dt = \int_{t_0=0}^t (V_0 + at) \, dt = \left[ V_0 t + \frac{1}{2} at^2 \right]_0^t$$

$$x - x_0 = V_0 t + \frac{1}{2} at^2$$

$$\boxed{x = x_0 + V_0 t + \frac{1}{2} at^2}$$

our formula from last week

So starting with  $a = \text{constant}$ , then we integrated twice, we get our formulas for  $V$  +  $x$

Forces: A force is something that pushes or pulls an object.

One "weight", which comes from gravity.



$$\text{weight} = \vec{F}_g = \text{force of gravity} = m \vec{g}$$

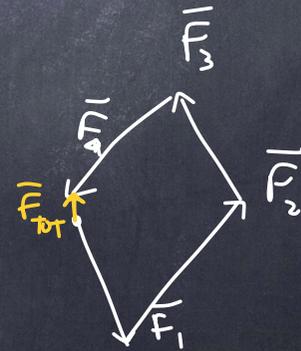
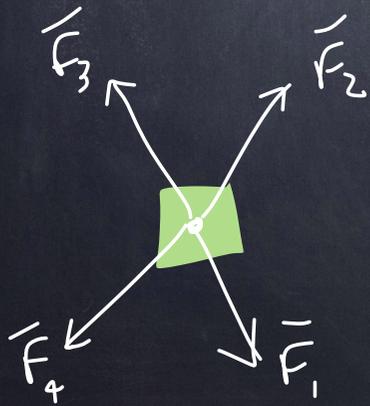
$\nearrow$  on earth                       $\uparrow$  mass                       $\uparrow$   $g = 9.81 \frac{m}{s^2}$

$\vec{g}$  points to the center of the earth

Forces are vectors, and can be added.

$$\vec{F}_{\text{TOTAL}} = \vec{F}_{\text{TOT}} = \vec{F}_{\text{NET}} = \sum_i \vec{F}_i$$

the "tail to tip" method.

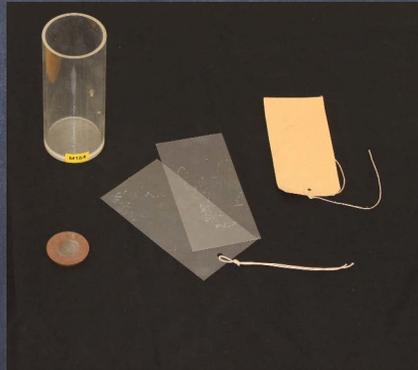


IF  $\vec{F}_{\text{TOT}} = 0$ ,  
there is no "net" force,  
we have equilibrium.



# Newton's three laws:

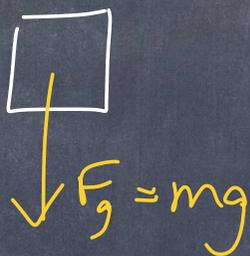
Law of inertia: 1) An object will remain at rest or continue to move in a straight line unless acted upon by a "net" force  
↑  
non-zero.



Newton's three laws:

2) A net force will cause an object to accelerate according to  $\Sigma \vec{F} = m\vec{a}$

A common example is a falling object

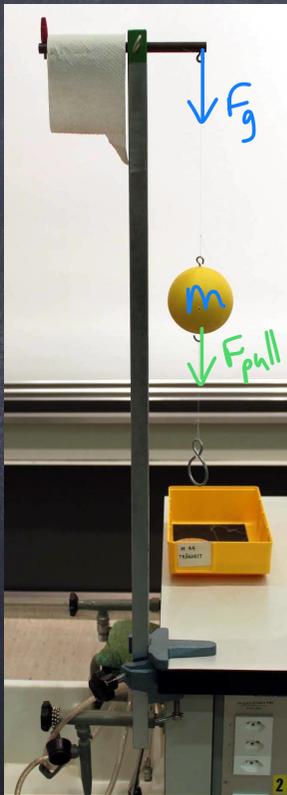


$$\Sigma \vec{F} = -F_g = -mg = ma$$

$$\text{so } \vec{a} = -\vec{g}$$

$$\begin{aligned} \Sigma F &= ma \\ \downarrow \\ mg &= ma \\ a &= g \end{aligned}$$

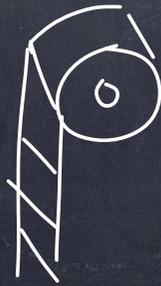
# Tests of Newton's first and second laws:



pull quickly: breaks on bottom string,  
(law of inertia)

pull slowly: breaks on top because  
there is more force  
top:  $\vec{F}_g + \vec{F}_{pull}$   
bottom:  $\vec{F}_{pull}$

toilet paper

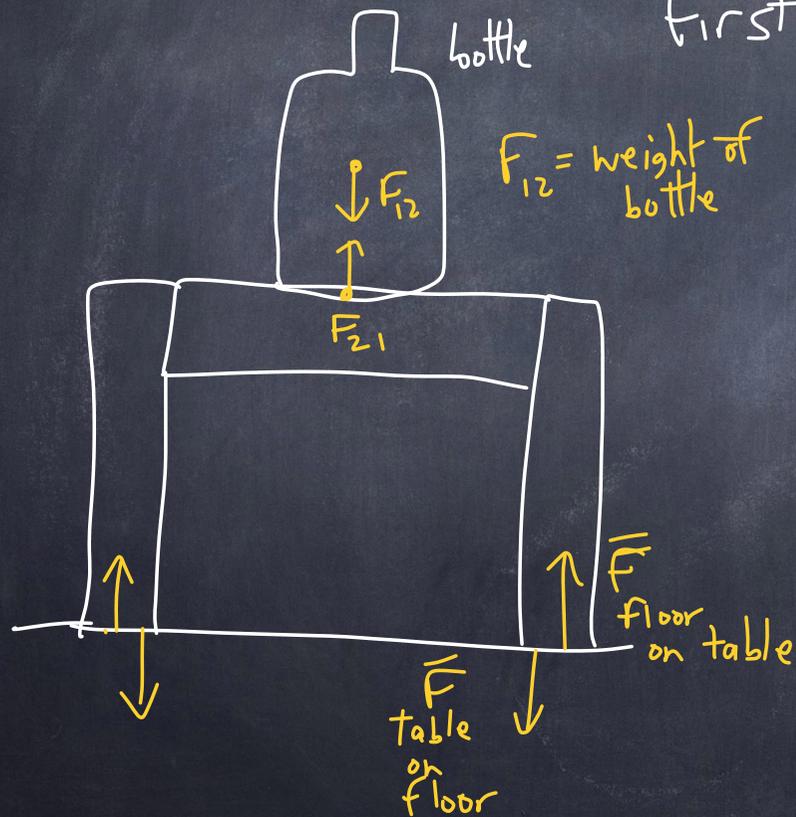


pull it fast: first law  
pull it slow: second law

Newton's third law:

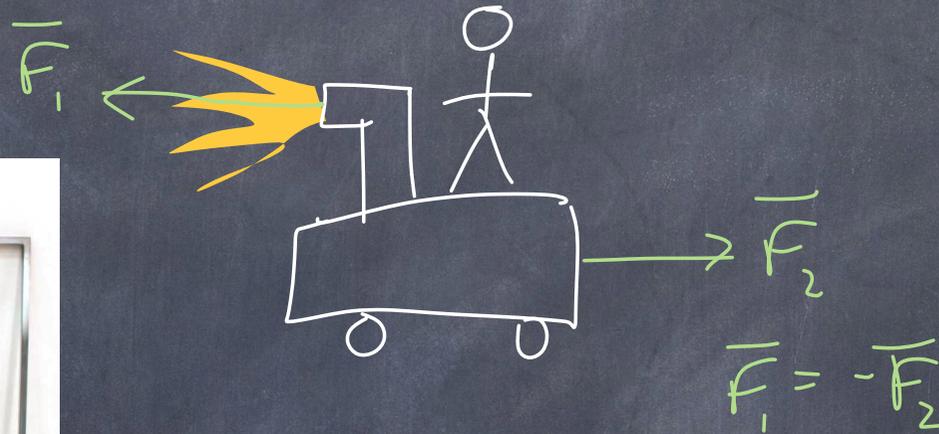
$$\vec{F}_{12} = -\vec{F}_{21}$$

3) when one object exerts a force on a second object, the second object exerts a force equal in magnitude, but opposite in direction, on the first object.



$\vec{F}_{12}$ : force exerted by object 1 on object 2.  
 $\vec{F}_{21}$ : force exerted by object 2 on object 1.

third law: action - reaction law



Summary: Newton's three laws:

Law of inertia 1) An object will remain at rest, or continue to move in a straight line unless acted upon by a "net" force  
↑  
non-zero total force

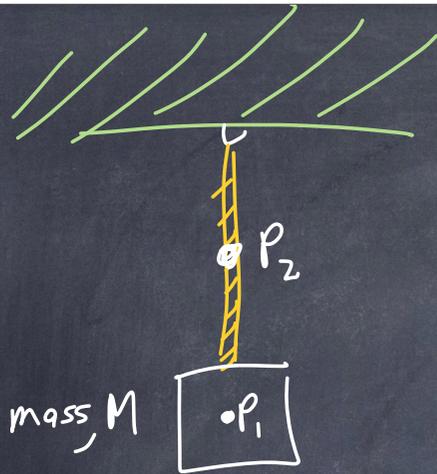
$$\underline{\Sigma \vec{F} = m\vec{a}}$$

2) A net force will cause an object to accelerate according to  $\Sigma \vec{F} = m\vec{a}$   
↑  
sum

$$\underline{\vec{F}_{12} = -\vec{F}_{21}}$$

3) When one object exerts a force on a second object, the second object simultaneously exerts a force equal in magnitude but opposite in direction on the first object.

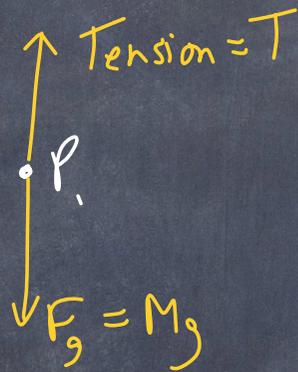
$$\vec{F}_{12} = -\vec{F}_{21}$$



A mass  $M$  hangs from a string to the ceiling.

Draw the forces acting on  $P_1$ .  
Or ... also on  $P_2$ ?

mass  $M$



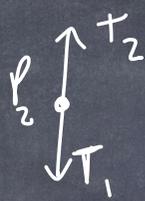
$$\Sigma F = \underbrace{F_g - T}_{T = F_g} = 0 = ma$$

But we must specify the direction + magnitude

$$F_g = Mg \text{ in } + \text{ direction}$$

$$T = Mg \text{ in } - \text{ direction}$$

What about  $\rho_2$ ?



$$\Sigma F = T_1 - T_2 = 0$$

$$T_1 = T_2$$

From previous page, we know that  $T = Mg$

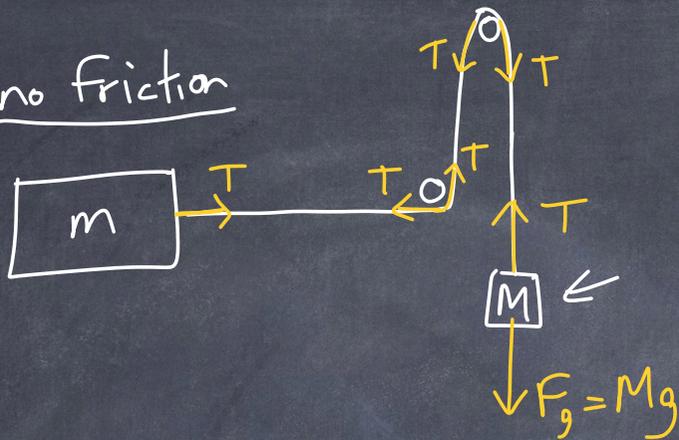
so here  $T_1 = Mg$  in  $(+)$  direction

$T_2 = Mg$  in  $(-)$  direction.

Tension has the same magnitude everywhere  
in the string.



assume no friction



$$M = 7g$$

$$m = 227g$$



$$\Sigma F = (\text{total mass}) a$$

$$Mg = (M+m) a$$

$$a = \frac{M(g)}{(M+m)} = \frac{(7)(9.81 \frac{m}{s^2})}{(227+7)} = \boxed{0.293 \frac{m}{s^2}} \text{ predicted}$$

measure

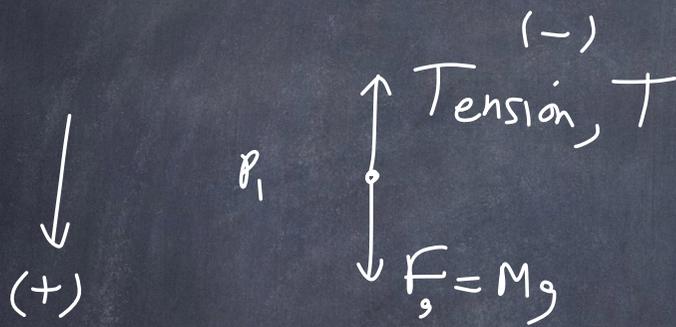
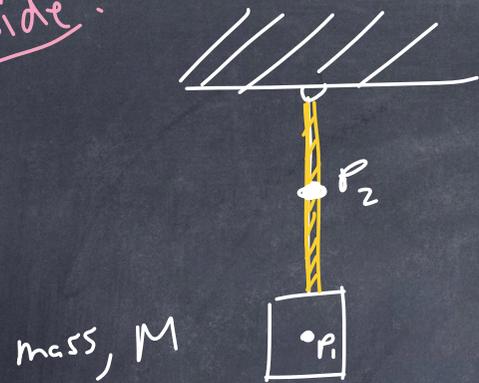
$$x = x_0 + v_0 t + \frac{1}{2} a t^2 = \frac{1}{2} a t^2 \rightarrow a = \frac{2x}{t^2}$$

$$x = 1.04 \text{ m}$$

$$t = ? = 2.8 \text{ s}$$

$$a = \frac{2(1.04 \text{ m})}{(2.8 \text{ s})^2} = \boxed{0.265 \frac{m}{s^2}} \text{ measured}$$

Aside:



If we use vectors for  $\vec{F}_g$  and  $\vec{T}$ , then we don't need to explicitly put negative signs in our sum,  $\Sigma \vec{F}$ .

$$\Sigma \vec{F} = \vec{F}_g + \vec{T} = 0$$

then  $\vec{T} = -\vec{F}_g$

so  $\vec{F}_g = Mg$   
 $\vec{T} = -Mg$

Exercise:

A mass  $M$  hangs from a string to the ceiling.

Draw the forces acting at  $P_1$ .  
What about  $P_2$ ?

If we use  $T$  and  $F_g$  as scalars, then we need to keep track of negative signs.

↓ We state  $T$  is in  $(-)$  direction

$$\Sigma F = F_g - T = 0 = ma$$

and  $T = F_g$

But we must specify the direction

$F_g = Mg$  in  $(+)$  direction

$T = Mg$  in  $(-)$  direction

↑  
← In both cases  $F_g$  points down  
&  $T$  points up.

Aside:

Sometimes people write  $\frac{df(x)}{dx}$  as  $f'(x)$ .  
These two are the same.

$$\text{Since } \frac{df(x)}{dx} = f'(x) \Rightarrow df(x) = f'(x) dx$$

And if you take the integral  
of both sides:

$$\int df(x) = \int f'(x) dx$$

This becomes:

$$f(x) = \int f'(x) dx$$

which is the definition of  
an integral

$$\text{Also, } \frac{d^2 f(x)}{dx^2} = f''(x)$$

