

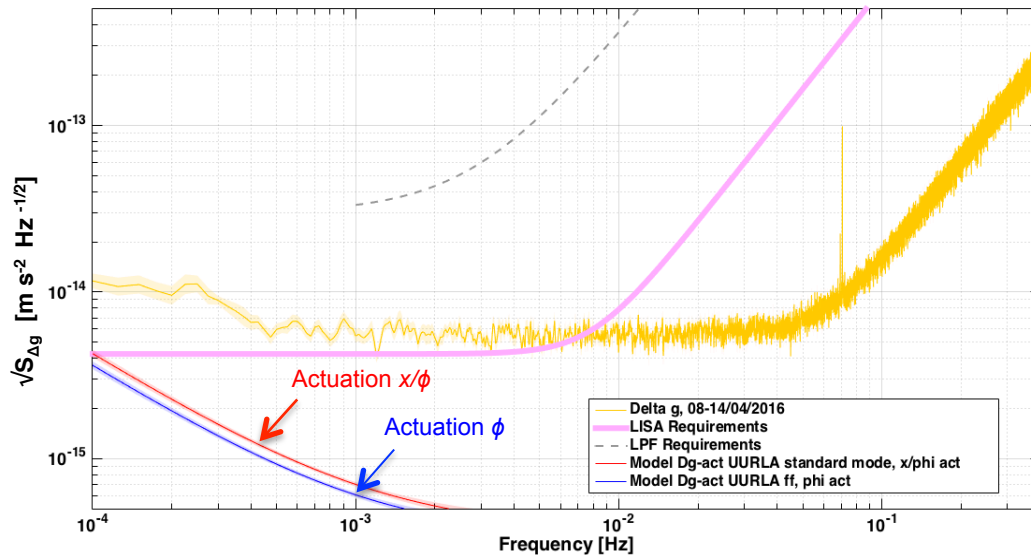
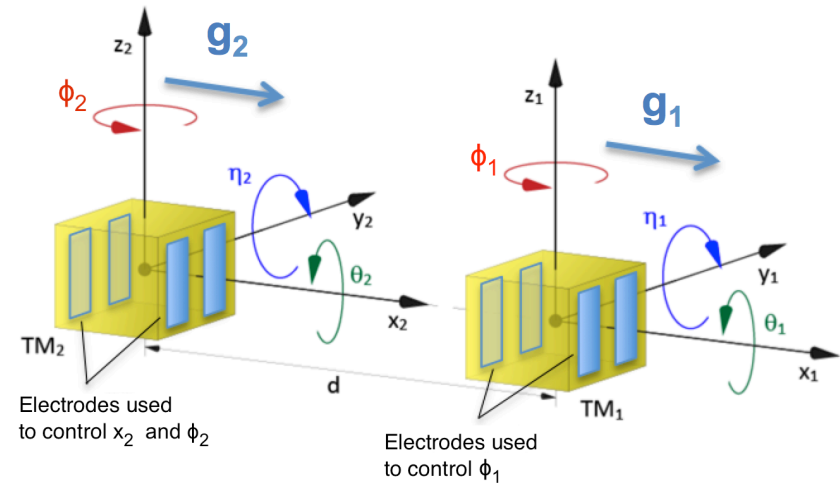
The free-fall mode experiment on LPF: first results

Roberta Giusteri on behalf of the LPF collaboration
University of Trento and INFN-TIFPA

LISA Symposium XI, 5 - 9 September 2016

LPF and actuation control

- LPF as an accelerometer
- Down-scaled version of one LISA arm
- TM1 “drag free” (geodesic reference)
- TM2 continuously controlled along x



[M Armano *et al.* PRL **116** 231101 (2016)]

$$F \propto V_{act}^2 \Rightarrow \delta(F) \propto 2F \frac{\delta V_{act}}{V_{act}}$$

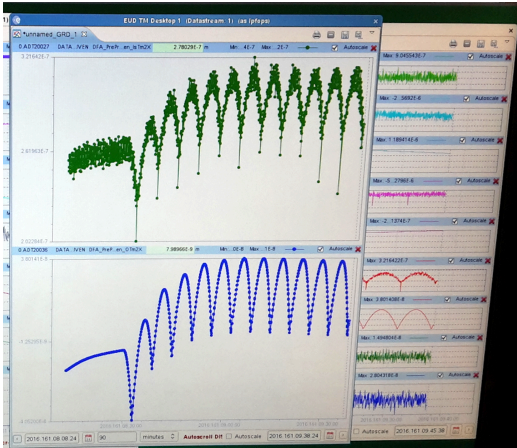
$$\Rightarrow S_{\Delta g}^{1/2} \propto 2 \Delta g_{DC} S_{\delta V_{act}/V_{act}}^{1/2}$$

$$S_{\delta V_{act}/V_{act}}^{1/2} \approx 5 \text{ ppm} / \sqrt{\text{Hz}}$$

Actuation along x not present in LISA

Free Fall experiment

- Proposed to subtract the actuation noise on TM2
- Actuation limited to short impulses
- Repeated stretches of parabolic flights

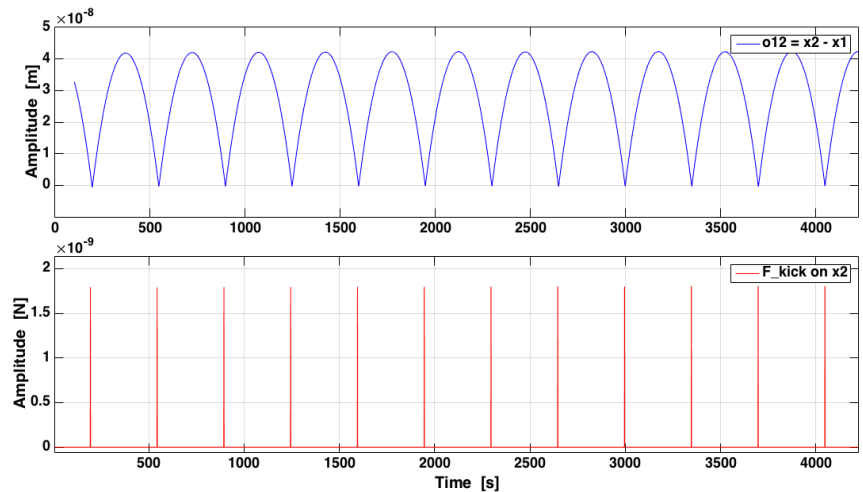
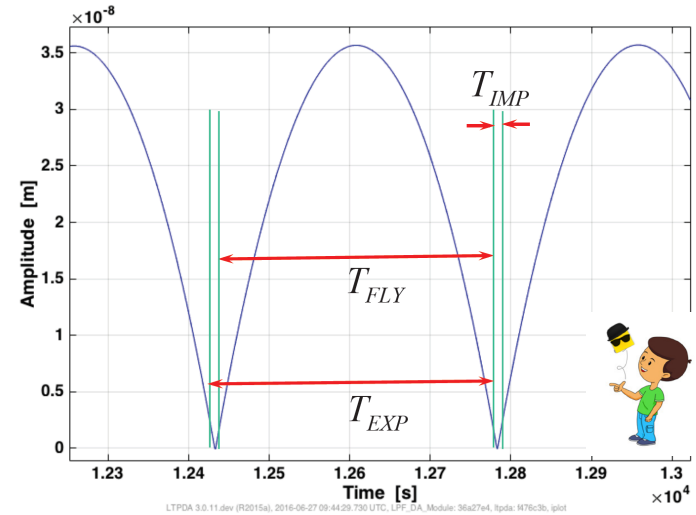


$$T_{fly} = 349.2 \text{ s}$$

$$T_{imp} = 1 \text{ s}$$

$$T_{exp} = 350.2 \text{ s}$$

$$f_{exp} \approx 2.85 \text{ mHz}$$

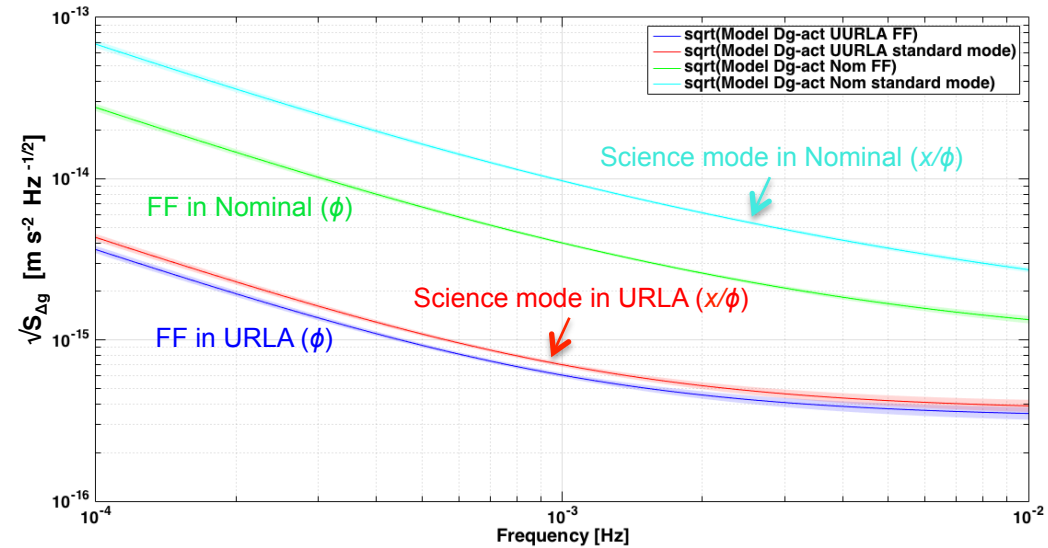


- No dependence on the actuator calibration
- Acceleration noise in “actuation-free” condition: characterization for LISA

FF mode vs standard science mode

Predicted actuation noise in different authority configurations →

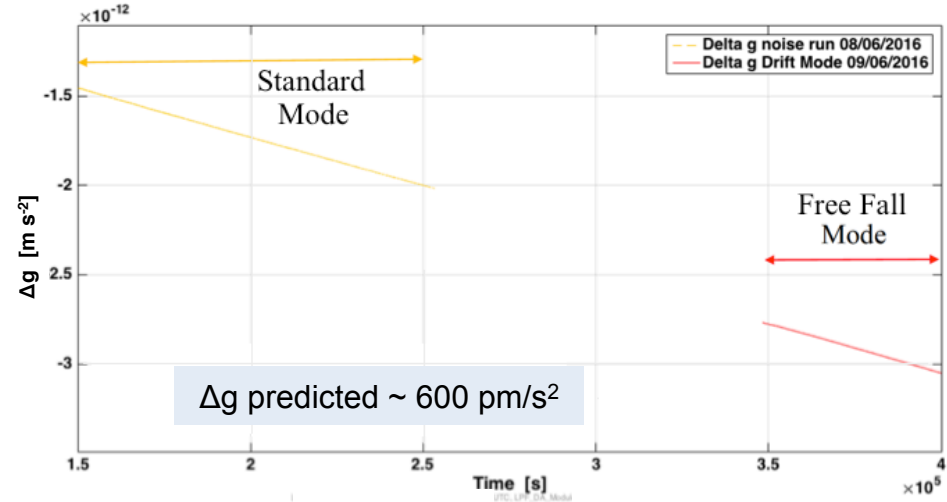
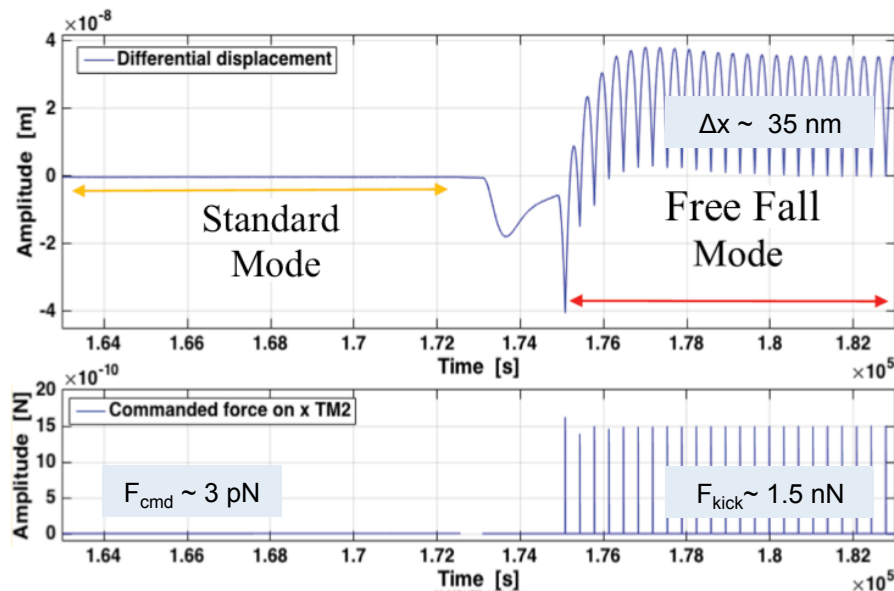
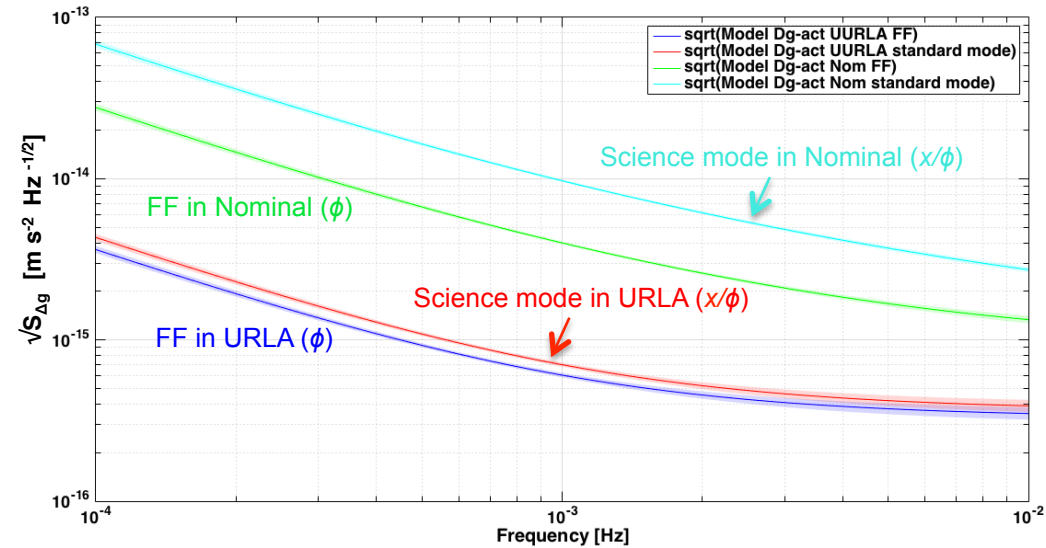
Nominal:	$F_{max\ x2} = 2200\ \text{pN}$
	$N_{max\ \phi2} = 10.4\ \text{pN m}$
URLA:	$F_{max\ x2} = 50\ \text{pN}$
	$N_{max\ \phi2} = 1\ \text{pN m}$



FF mode vs standard science mode

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Experiment calibration

Equation of motion to fit:

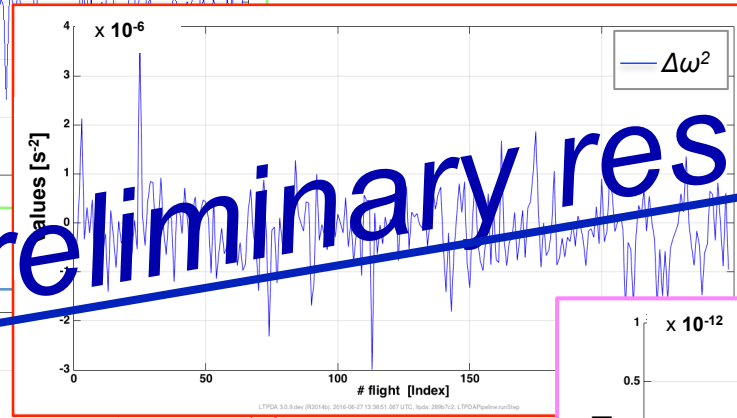
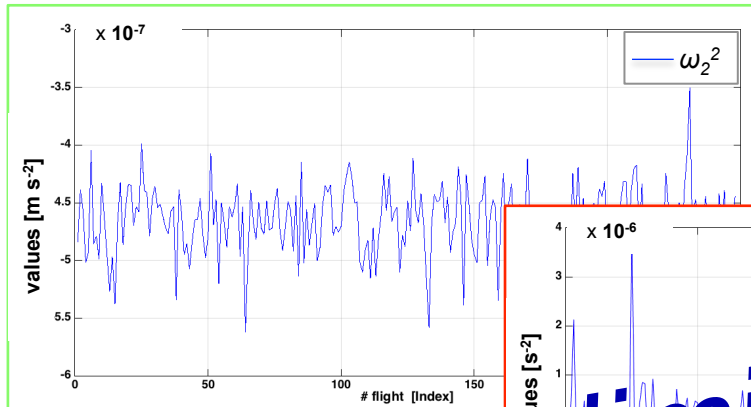
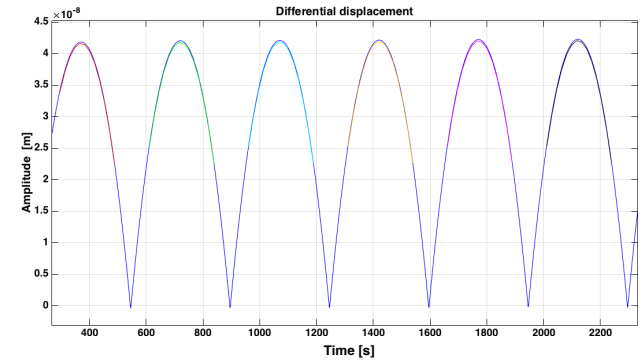
$$\Delta \ddot{x} = -\omega_2^2 \Delta x - \Delta \omega^2 (x_1 - x_{SC}) + \Delta g + \dot{g}_0 \cdot t$$

Filtering and decimation:

$$T_{\text{samp}} \sim 17 \text{ s}$$

$$f_{\text{samp}} \sim 57 \text{ mHz}$$

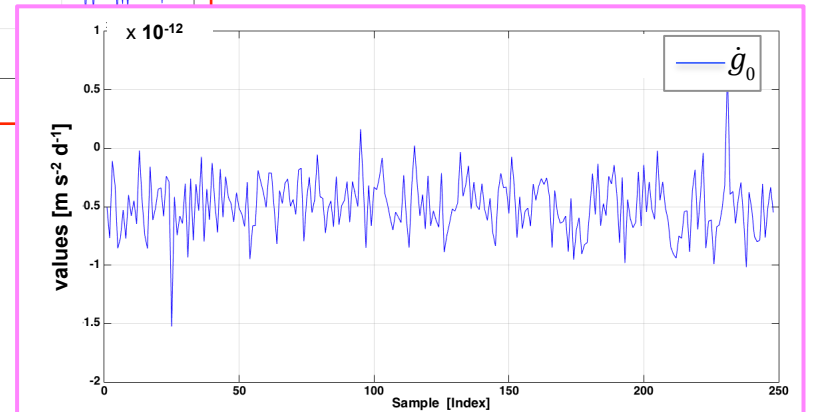
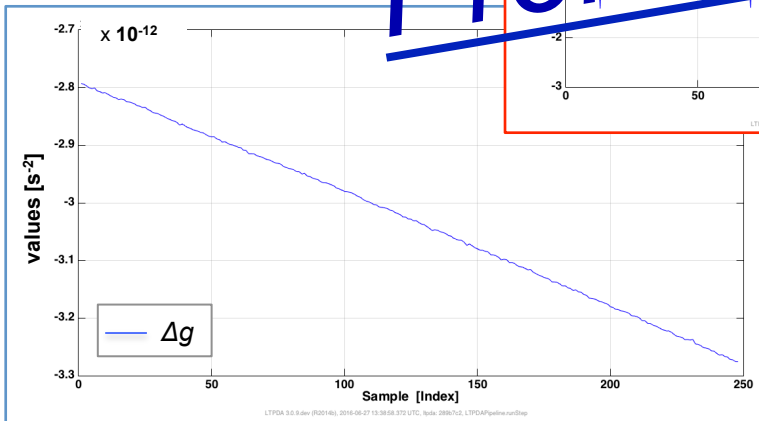
$$n_{\text{fit}} = 14$$



Parameter	Mean value	Error
ω_2^2 [10 ⁻⁷ s ⁻²]	- 4.661	0.019
$\Delta \omega^2$ [10 ⁻⁷ s ⁻²]	- 1.289	0.461
Δg [μm s ⁻²]	- 3.031	0.009
\dot{g}_0 [pm s ⁻² d ⁻¹]	- 0.493	0.016

Preliminary results

[FF on June 10th in URLA authority]



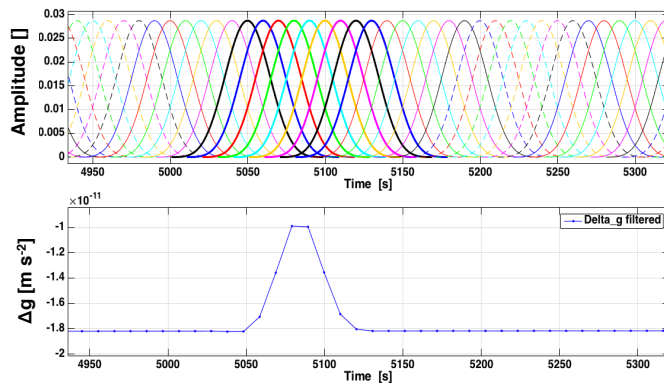
Data analysis challenge

Kicks: high-noise configuration
analysis of “actuation-free motion” → gaps in data

Analysis techniques:

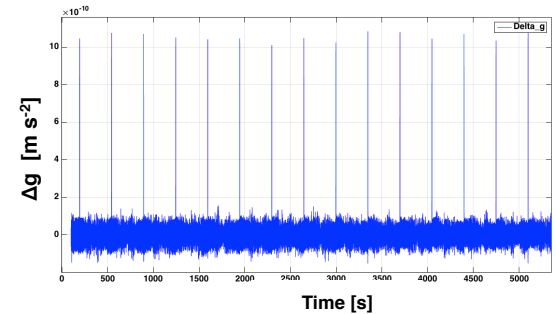
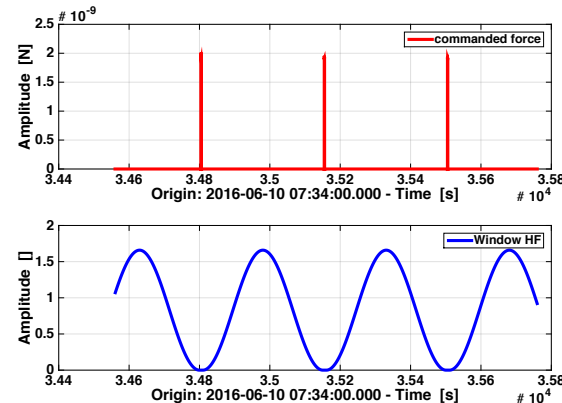
Blackmann-Harris low pass filtering

low pass filtering + downsampling
and set kicks to zero



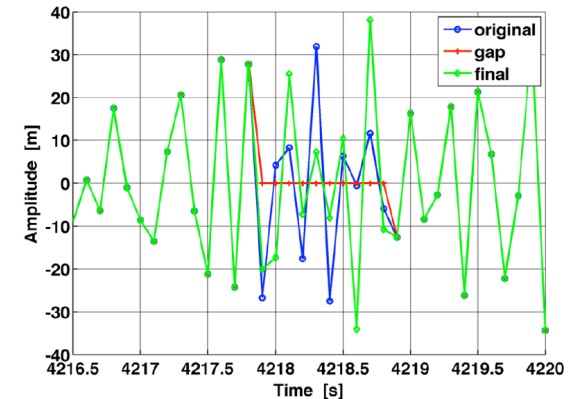
Windowing technique

masking the gaps with
spectral windows



Constraint-Gaussian Gap Patching

filling the gaps with
artificial data

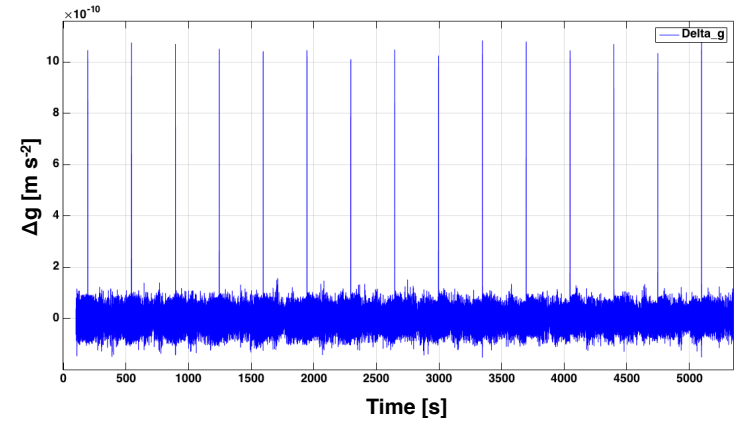


[Poster: G. Russano “LISA Pathfinder Free Fall Mode”, A18]

BH low pass approach

Δg estimation at 10Hz

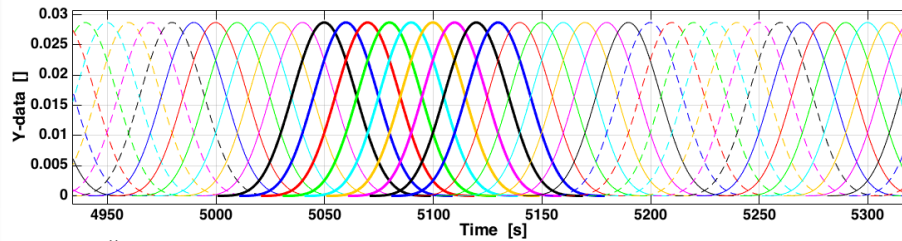
$$\Delta g(t) = \Delta \ddot{x} + \Delta \omega^2 (x_1 - x_{sc}) + \omega_2^2 \Delta x - \dot{g}_0 \cdot t$$



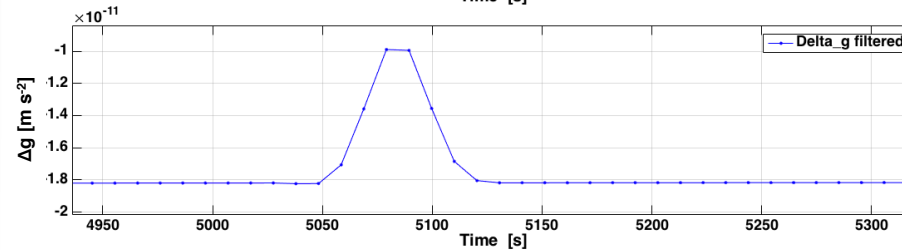
BH low-pass filter

- n_{tot} per T_{exp} , n_{keep} per T_{fly}
- $T_{samp} = T_{exp} / n_{tot}$
- BH window, $T_{win} = T_{fly} - 2 \cdot margin - (n_{keep} - 1) \cdot T_{samp}$
- filtering and downsampling

Set to zero
 $n_{gap} = n_{tot} - n_{keep}$



Evaluate the spectrum



PSD correction for n_{tot}/n_{keep} and BH transfer function

Configuration:

n_{tot}	34
n_{keep}	25
n_{gap}	9
T_{samp} [s]	10.3
f_{samp} [mHz]	97
margin [s]	2
T_{win} [s]	98

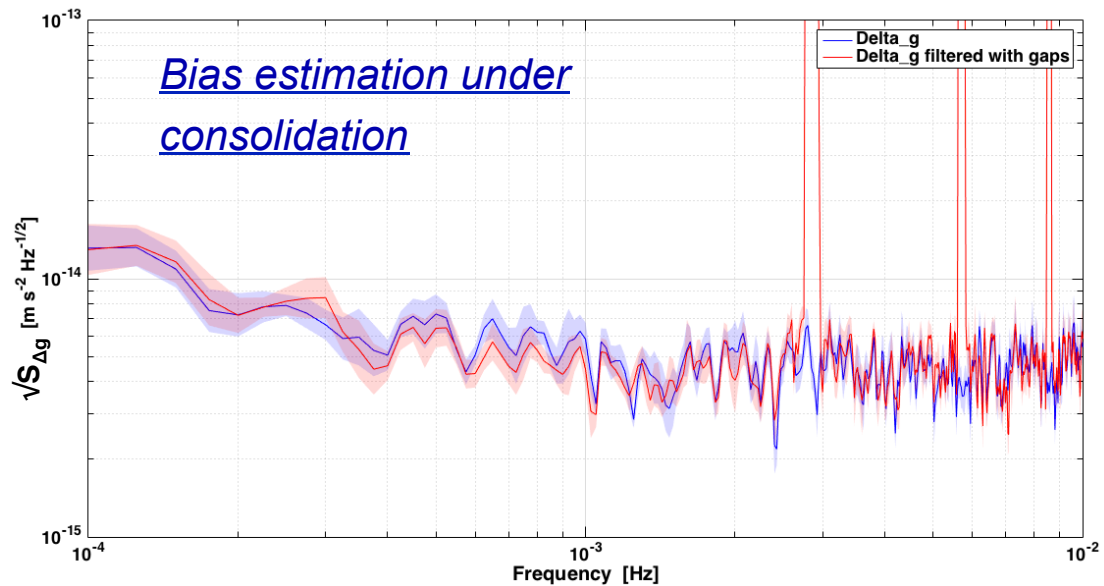
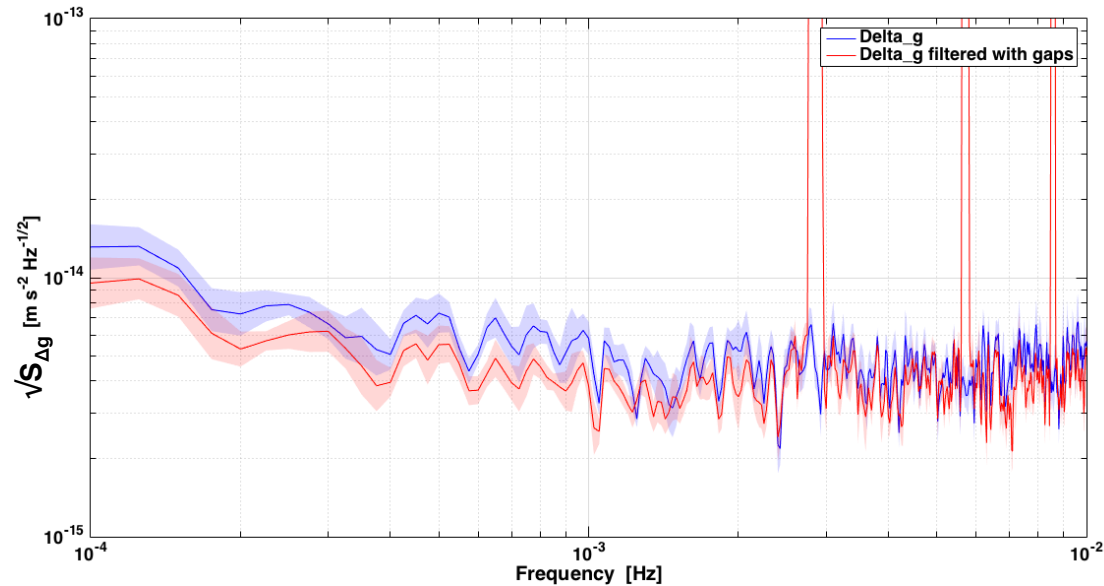
Calibration of BH technique

Investigation into the **potential BIAS** introduced by the BH technique:

1. Science measurement (URLA, May 16-18)
2. Apply BH filtering method
3. Insert artificial gaps
4. Estimate the spectrum
5. Correction for filter transfer function

Bias estimation necessary to correct the spectrum accurately.

Correction related to $n_{\text{tot}}/n_{\text{keep}}$
(work in progress)

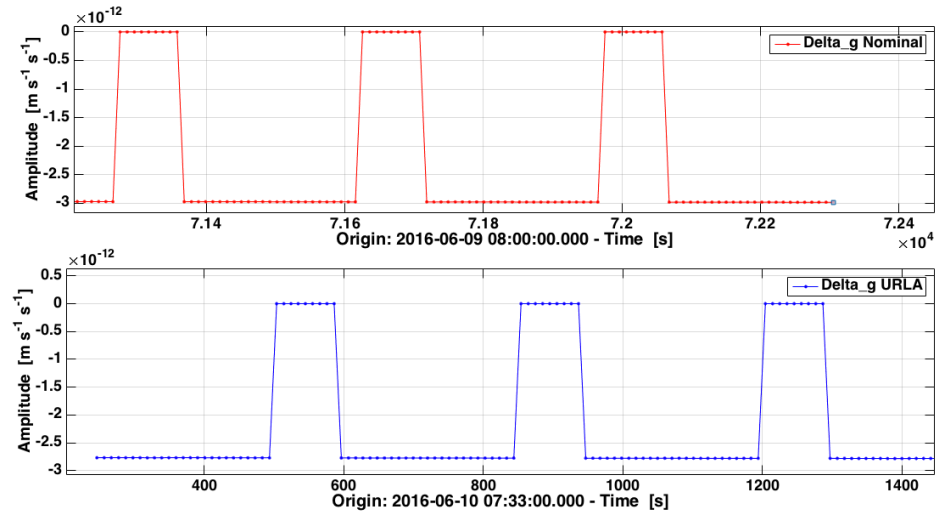


First results applying BH method

FF Nominal x/ϕ authority on TM2, 1 day

($F_{max} = 2200$ pN , $N_{max} = 10.4$ pN m):

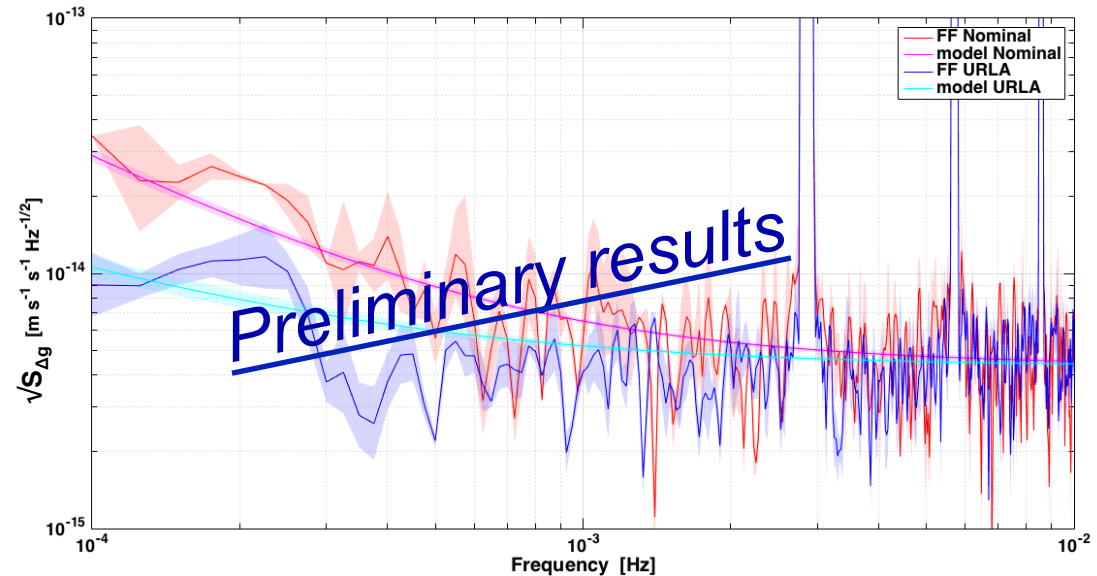
Parameter	Mean value	Error
ω_2^2 [10^{-7} s^{-2}]	- 7.116	0.029
$\Delta\omega^2$ [10^{-7} s^{-2}]	- 1.715	0.403
Δg [pm s^{-2}]	- 2.500	0.007
\dot{g}_0 [pm $\text{s}^{-2} \text{ d}^{-1}$]	- 0.400	0.021



FF URLA x/ϕ authority on TM2, 1 day

($F_{max} = 50$ pN, $N_{max} = 1$ pN m):

Parameter	Mean value	Error
ω_2^2 [10^{-7} s^{-2}]	- 4.586	0.019
$\Delta\omega^2$ [10^{-7} s^{-2}]	- 1.271	0.407
Δg [pm s^{-2}]	- 3.029	0.009
\dot{g}_0 [pm $\text{s}^{-2} \text{ d}^{-1}$]	- 0.493	0.016

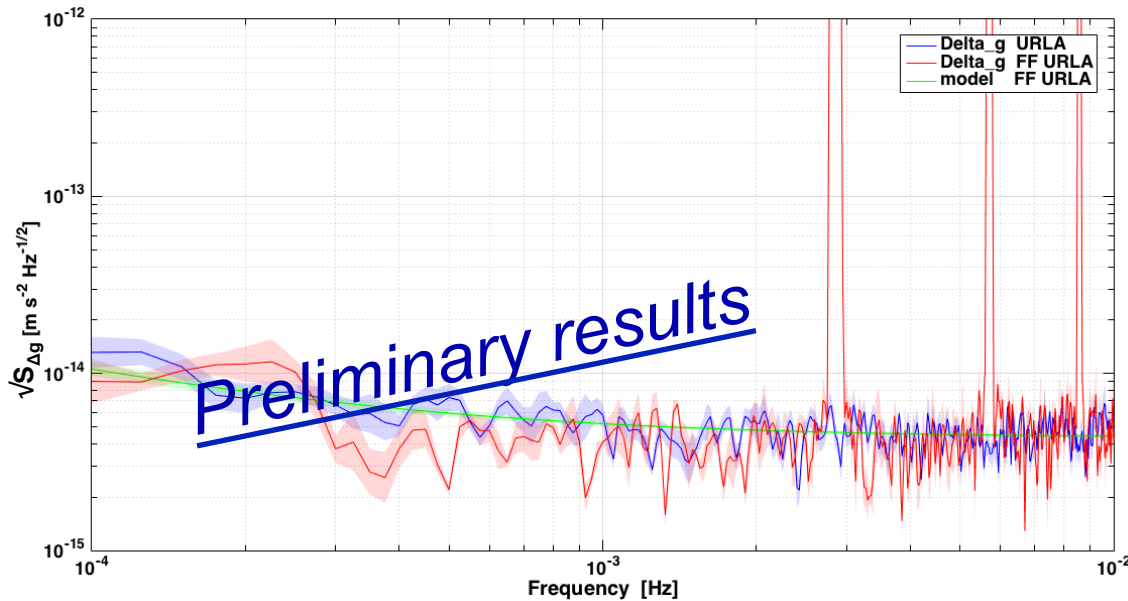
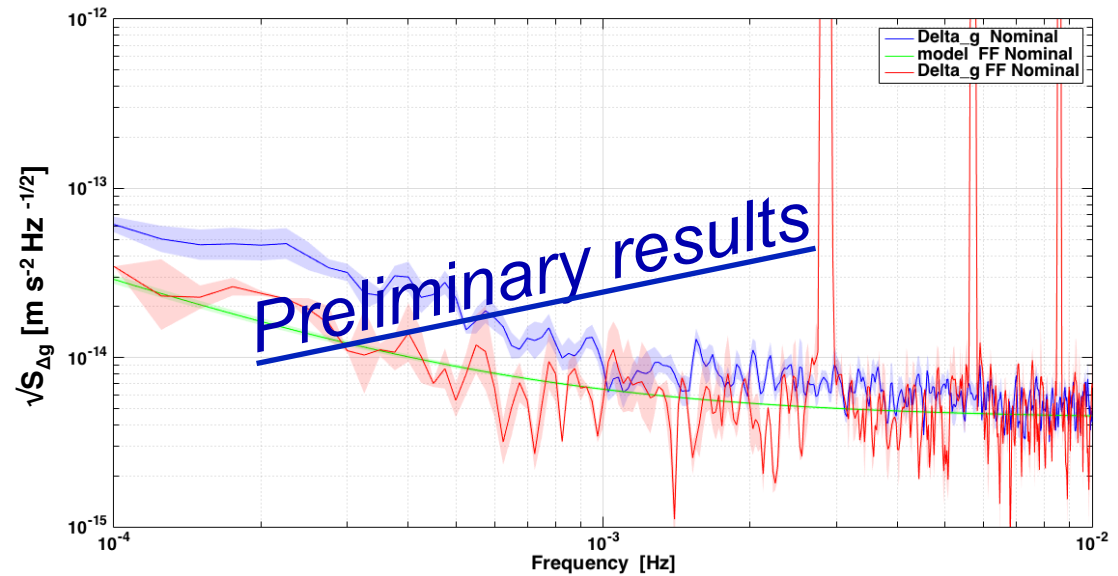


Comparison with standard mode

Nominal authority:

Science mode: May 19-21

Free Fall: June 9th



URLA authority:

Science mode: May 16-18

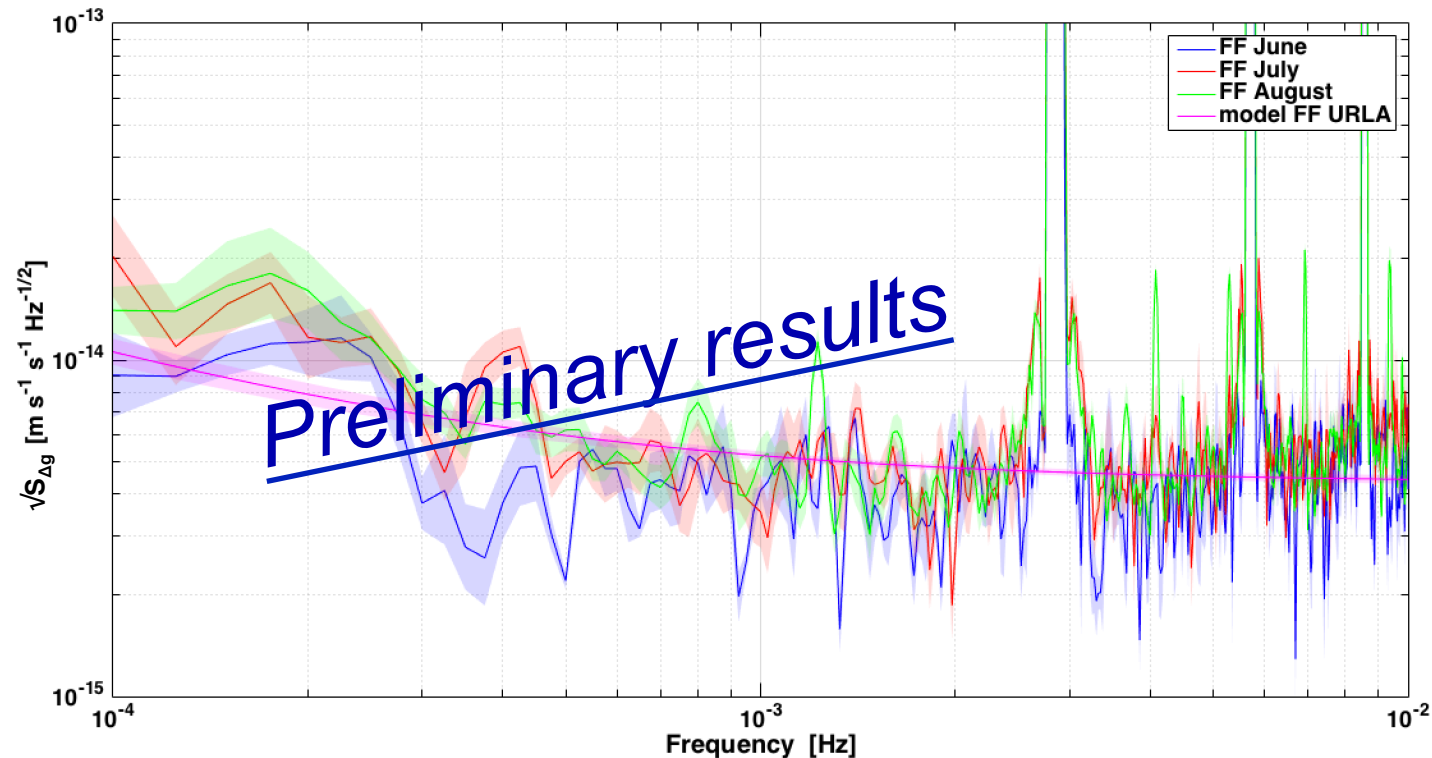
Free Fall: June 10th

Comparison among all FF runs

URLA authority,
BH technique applied

Averaged spectral values in [0.1, 0.4] mHz band

FF run	\sqrt{S} [fm s ⁻² Hz ^{-1/2}]
June run (1 d)	9.464 ± 0.473
July run (1.5 d)	15.302 ± 1.750
August run (3 d)	12.384 ± 1.159



- **Free-fall mode control** achieved and maintained
- All analysis techniques have extracted spectra
- Free Fall results consistent with **actuation models** predicted
- Free Fall results consistent with **long science measurements (URLA)**

Future work:

- ❑ Analysis **consolidation** of the two last FF experiments
- ❑ Correction for **BIAS** introduced by each method
- ❑ **New Free Fall experiment** in same conditions of the first one (and longer)
- ❑ **New design Free Fall experiment with kicks also on ϕ_2**

Perspectives:

- Free Fall implementation → closer to **LISA performance**
- Spectral estimation in presence of gaps

Thank you

